Infliction of Reality Upon Virtual Models

"Digital Physicality | Physical Digitality"

Prague, 14. 09. 2012



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Infliction of Reality Upon Virtual Models

Concept of the compilation

How it started ... (... and continued here)

If it is real, how can it be inflicted, maybe augmented? Some examples and remarks about AR/MR, especially Markers

Experiment

There will be no conclusion





Infliction of Reality Upon Virtual Models The ACADIA's general list:

"Digital Physicality | Physical Digitality"

Wassim Jab: <peeking his head up to see what all the excitement is about>

Volker Mueller: <picking up where Wassim left off:>

electronic - digital digital - analog - hybrid digital - non-digital digital - real digital - material digital - physical built (physical) drawing - actual work idea digital models - analog modls proper education computer/virtual virtual models - physical models model - real digital/virtual - real world materiality real simulated realities of the situation - perfect digital simulation digital technologies mediation information - communication simulation practice - education responsible practice

Inputs from Brian Johnson, Ted Hall, Murali Paranandi, Rich Nitzsche, and others,

Henri still on defense

Werner missed 2 points lafter 3 days of discussion): a) There is an existing model in Augmented Reality: the Milgram- continuum. b) Discussions in architecture have almost always an inherent aspect of Utopia.



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it somehow.

Henri did start

Henri's defense

Infliction of Reality Upon Virtual Models Continuation here at the conference: "Digital Physicality | Physical Digitality"

... taken some notes in Prague, neat picking:

"virtual forces"

"visual voids"

"Interreality"

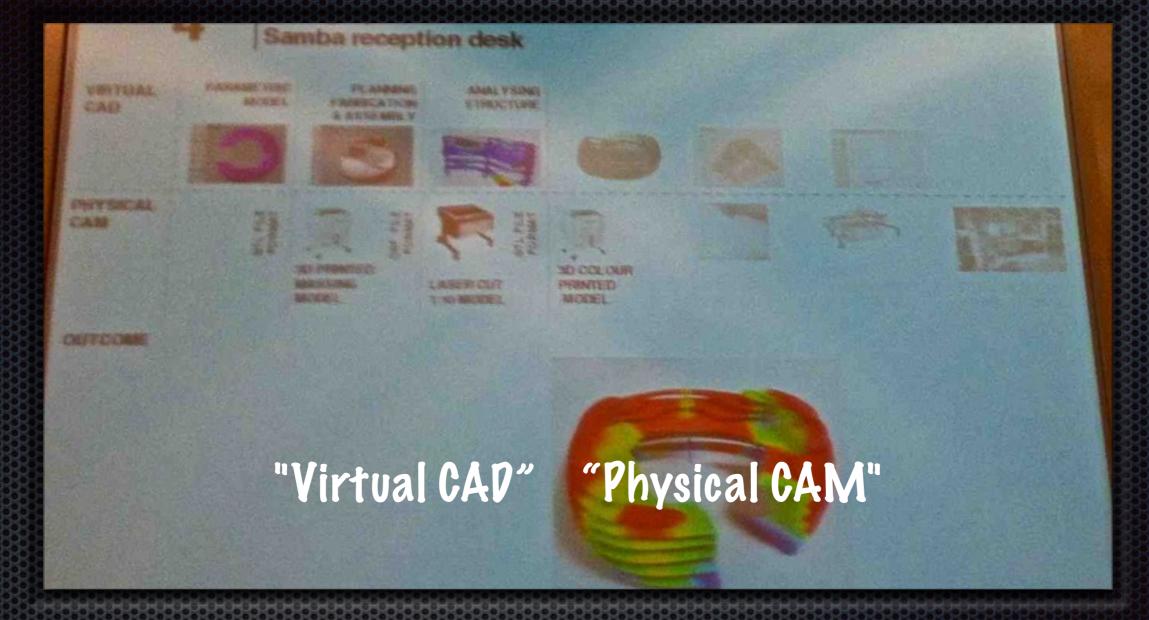
What are we dealing with?

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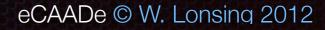
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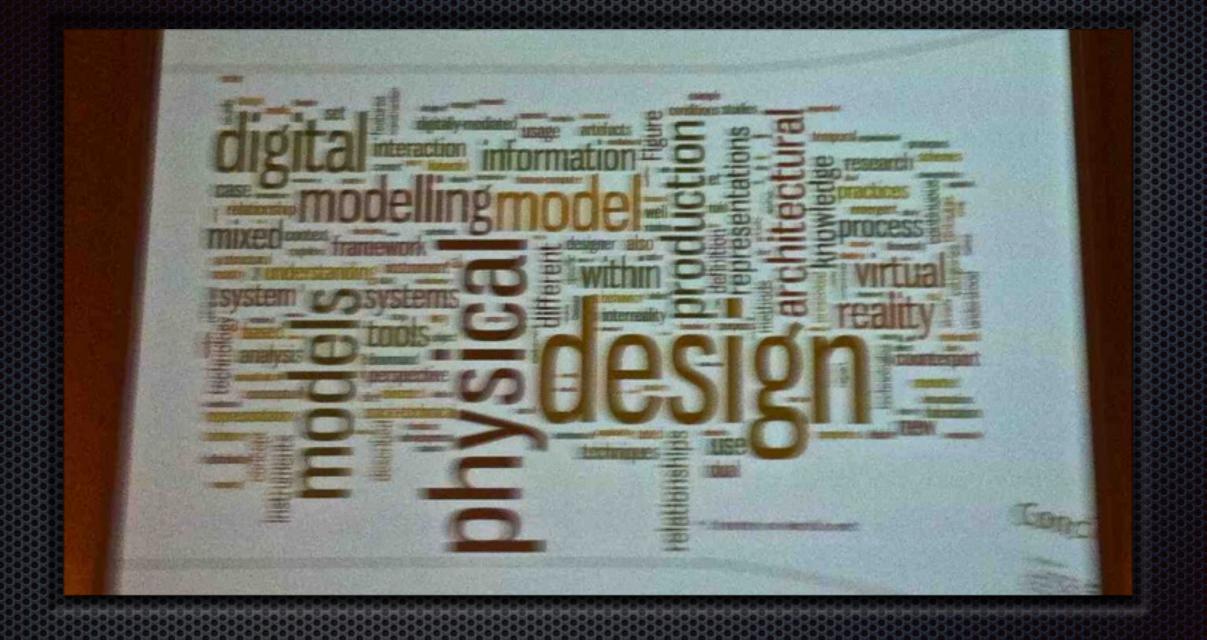
by [163], Samba reception Desk







Wordcloud by [138]

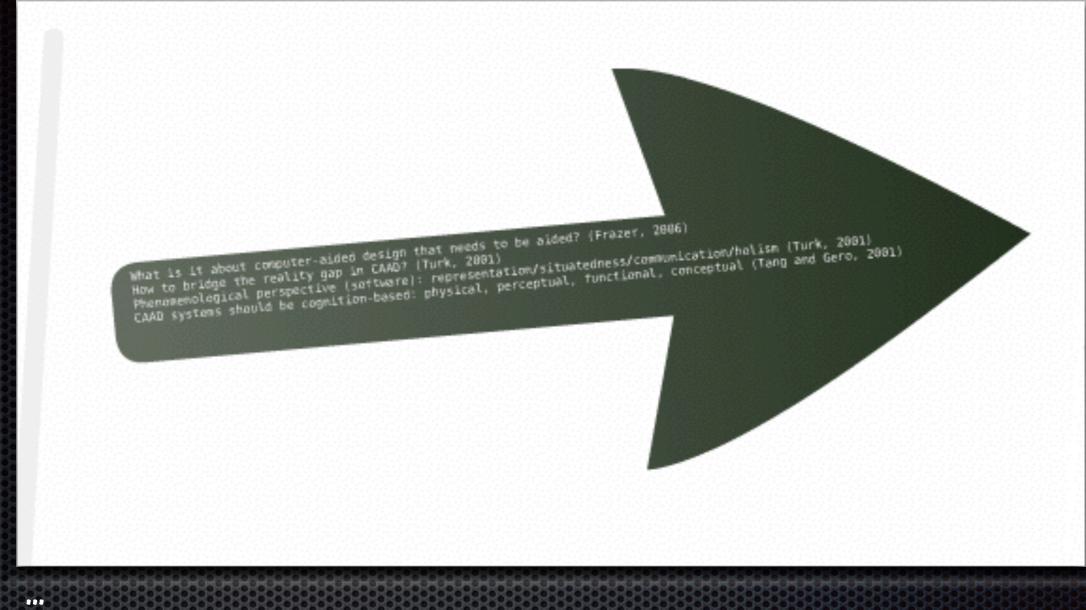


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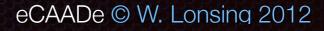
Questions from [138]



How to bridge the reality gap in CAAD? [Turk 2001]

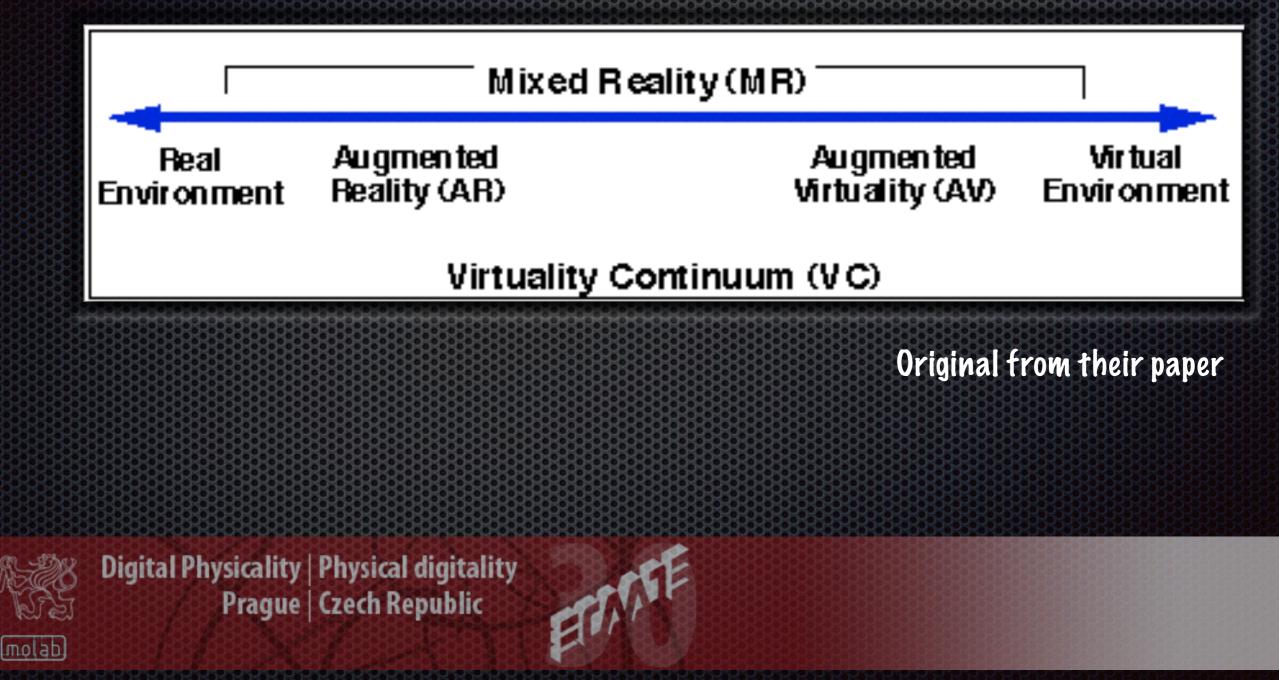






Milgram Continuum

Paul Milgram and Fumio Kishino (1994): A TAXONOMY OF MIXED REALITY VISUAL DISPLAYS

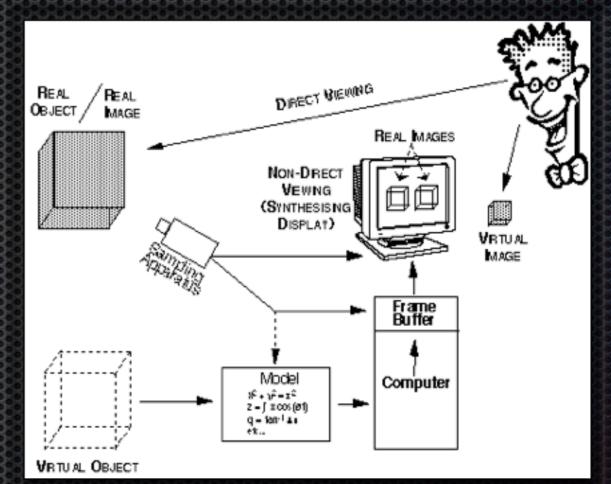


Paul Milgram and Fumio Kishino

A TAXONOMY OF MIXED REALITY VISUAL DISPLAYS

Augment Reality with 2 views, one directly into the real world the other into a virtual world.

Composition of images.



Original from their paper





Introducing Augmented Reality

Invented by Boeing in the late 80s, early 90s. Inspired by the movie Top Gun, with Tom Hanks. Others: Mixed-, Composed-, Hybrid Reality or - Virtualiy; Hybrids; Hybrid Space etc.

10+ years of silent devlopment, only for insiders. First booth after 2000 Since 2007 common on smart phones.

Explanation: To become real, it has to be in real time.





Augmenting Reality...



... maybe is related to computation, but not necessarily



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Explaining Augmented Reality

Augmented Reality is understood as visual augmentation.

A registrated camera provides images from the real world. A virtual image is rendered accordingly. Both images are composed into one composite image.

Haptical augmentation. Olfactional augmentation.





Tracking based AR as on smart-phones

Pro:

Affordable with in-built GPS etc. Everywhere accessable, deployable etc.

Con:

Delayed processing Images are not really synchronized, jagged.









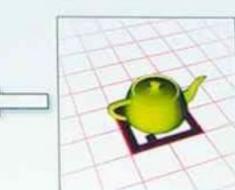
How Marker Tracking Works











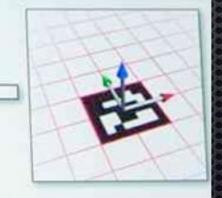
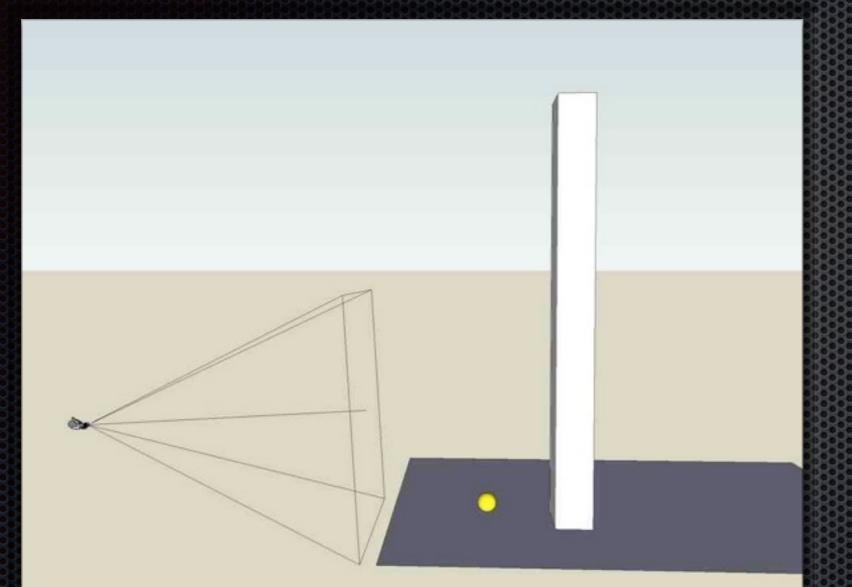


Image courtesy Daniel Wagner, T U Graz





Marker and Tracking based AR



Combination of both systems for large scale outdoor augmentations

Camera with viewing volume, model and fiduciary feature



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USP No. 7,391,424

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About Augmenting Reality ...







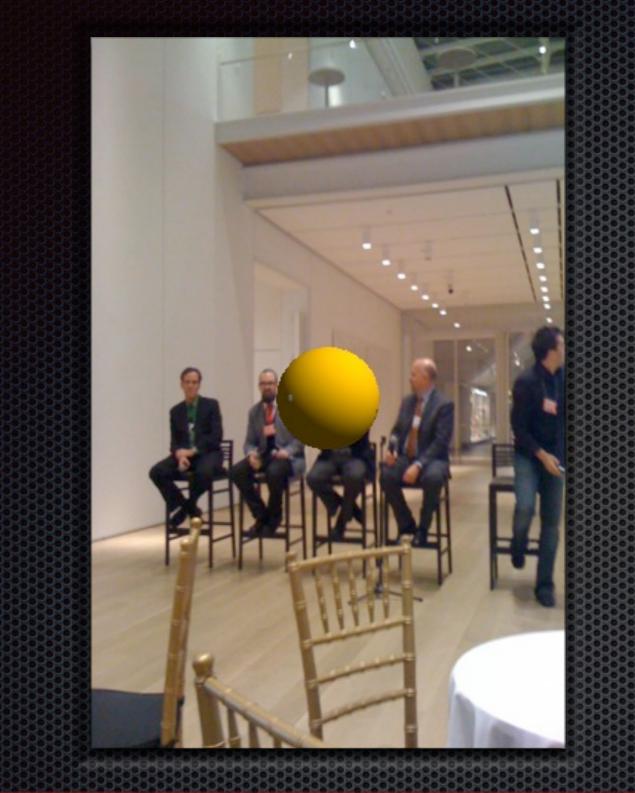
... or the composition of images.

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ACAPIA conference Chicago 2009

Panel discussion

Screenshot of a live Augmentation with an iPhone 3G W. Lonsing

on the right: Tristan d'Estree Sterk





Examples



Column in a backyard



by Peter Anders

Shapes, only one is real.



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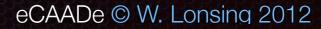


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lifeClipper3 by Jan Torpus,

Setup: HMD, earphones and backpack Tracking based. Outdoor, but needs guidance. Single user experience

Result: Unique spatial impressions in space and time.

Imolabl





Toelnput



Toe Input with Mobile Projector and Depth Camera

by: Daiki Matsuda, Keiji Vemura, Nobuchika Sakata, Shogo Nishida

...search on Youtube

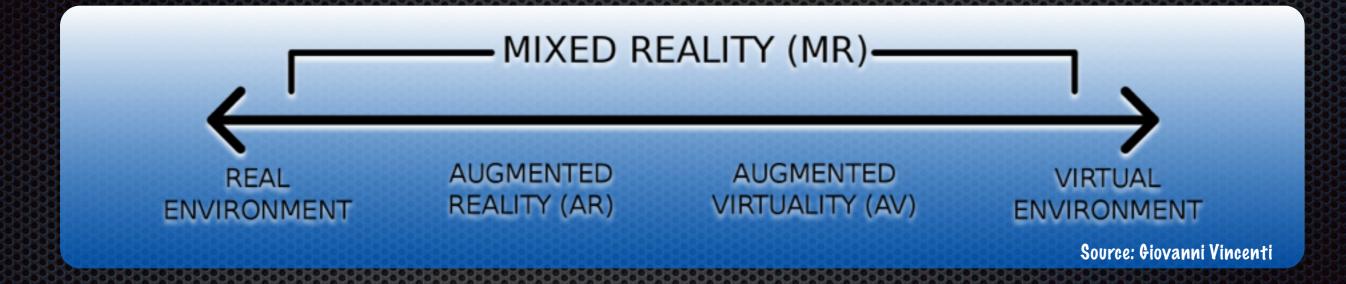






Milgram Continuum

Paul Milgram and Fumio Kishino: Virtuality Continuum Enhanced presentation.



This principle is subject to a lot of variations





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Appearances

Virtuality: Physical presence of a technical machinery

Reality: Acts as blue-print for virtual models.









Concepts introduced:

- Gravity - Lighting - Color
- Solid Objects

Usage: Physical Engine





Total immersion

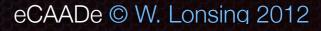


The technical machinery demonstrating its real presence.











Markers are inflictions on purpose.



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Fiduciary feature:

Captured balloon: - diameter: 3 m

- max. height: 100 m
- volume: 20 cubic m





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Large scale fiduciary feature in the air.



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Marker: Hidden Pattern Instead of markers the QCAR SDK provides image targets. Images are uploaded, examined and processed.



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Marker: Hidden Pattern

These Markers have a dual nature, with or without a computational device.

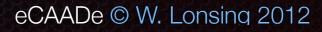


Marker image from the Qualcomm SDK

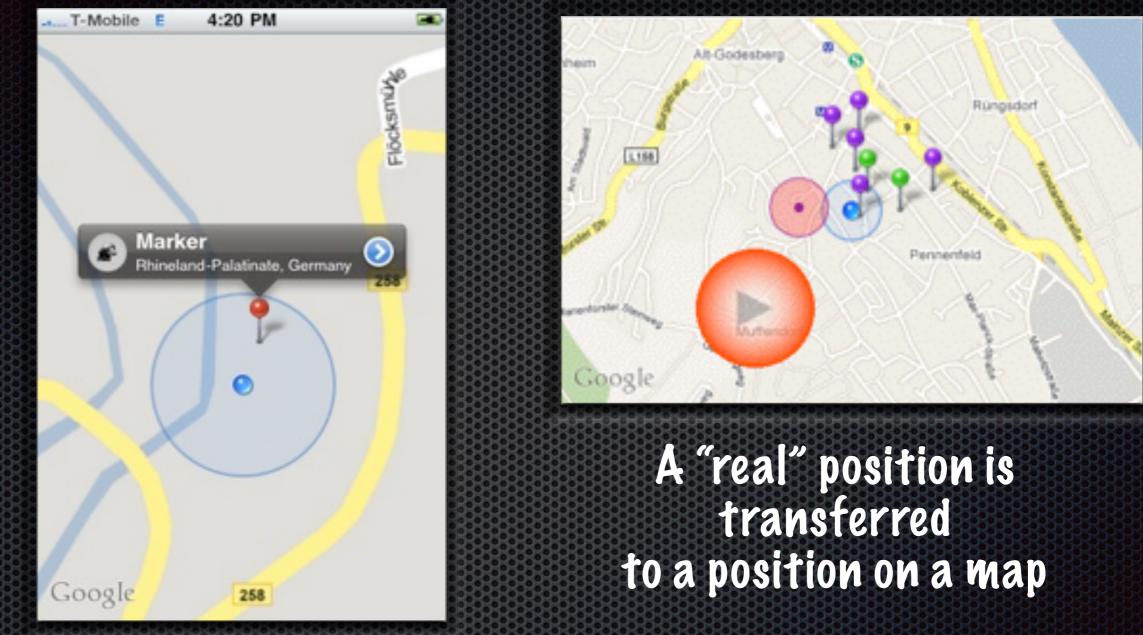
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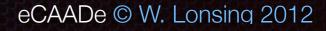


Reflections on the map









Other infliction:

e.g. disabilities

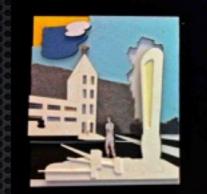






Infliction: Visually impaired







Neo Rauch, "Mittag", 1997

Haptic paintings [133]:

Using rapid prototyping technologies to grant visually impaired persons access to paintings

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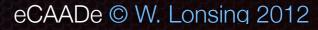




Two images are following....







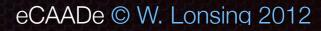
Experiment





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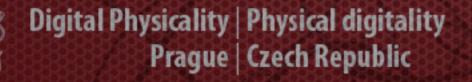


Experiment





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A

The difference is time.

Where are the differences?



B







Reality



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The stone is not a stone



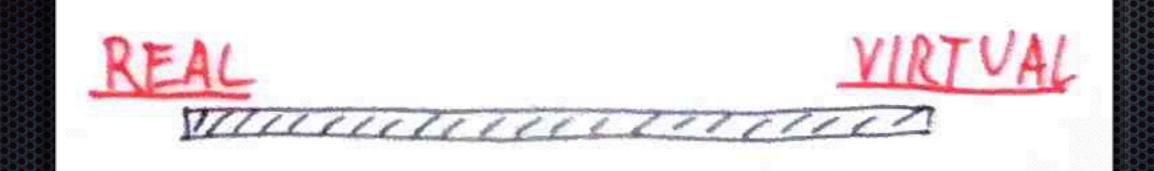
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Simplified Continuum



based on Paul Milgram and Fumio Kishino (1994)

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