

Designing Virtual Models in Real Space

Werner Lonsing, Bonn, Germany

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Designing Virtual Models in Real Space

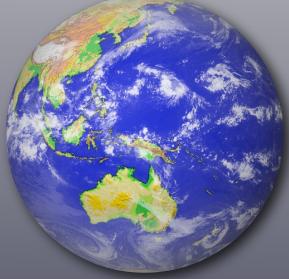
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Designing Virtual Models in Real Space

- System Hardware • Aspects of Software
 - Aspects of Software



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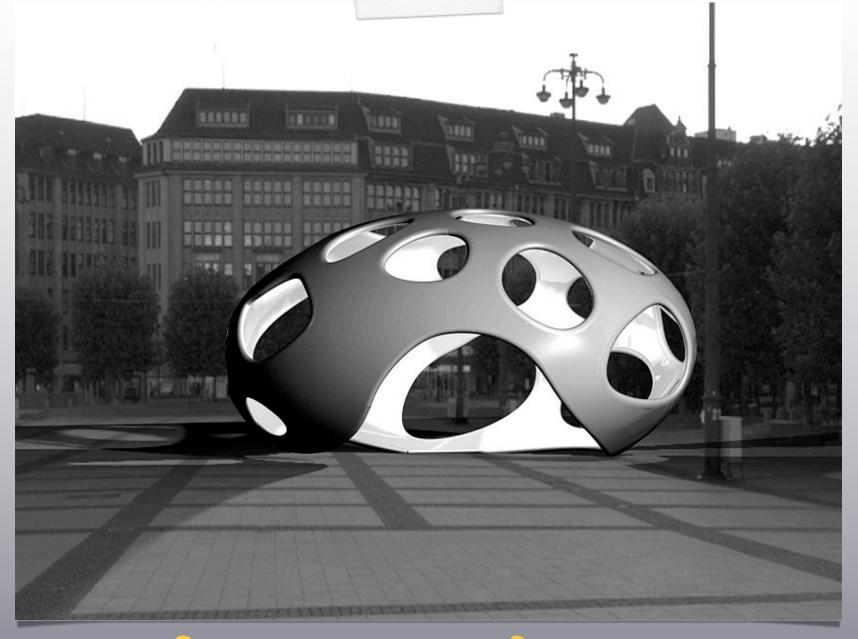


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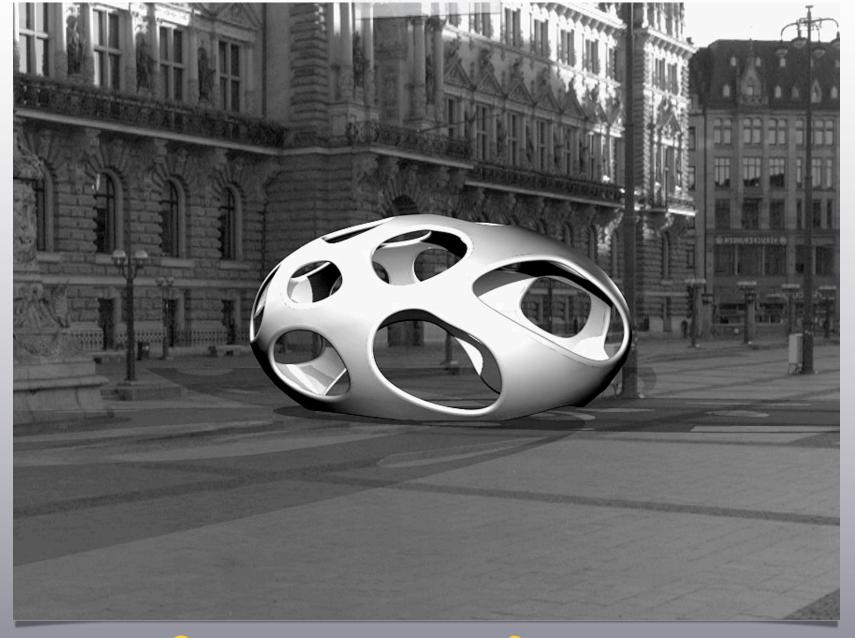
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Composite Mage Jürgen Fedele di Catrano: Tetrapod Wie es (euch ge)fällt TU Vienna (B. Martens)



Composite Mage Michael Murauer: Stadtausschnitte TV Vienna (B. Martens)



Composite Mage Michael Murauer: Stadtausschnitte TV Vienna (B. Martens)



Composite Mage Peter Anders: Working with the AmbiViewer Backyard in Midland, MI



Composite Mage Peter Anders: The K-house Backyard in Midland, MI

Composite Movie Movie with simple shapes created with the AmbiViewer Frida in Mexico



COMPOSITE MOVIE Movie with simple shapes created with the AmbiViewer

Frida in Mexico

Composite Movie Movie with simple shapes created with the AmbiViewer Frida in Mexico



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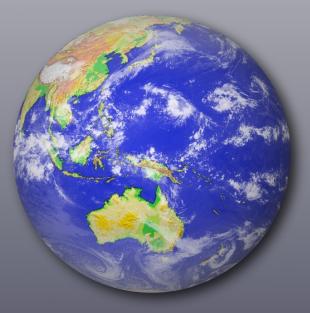
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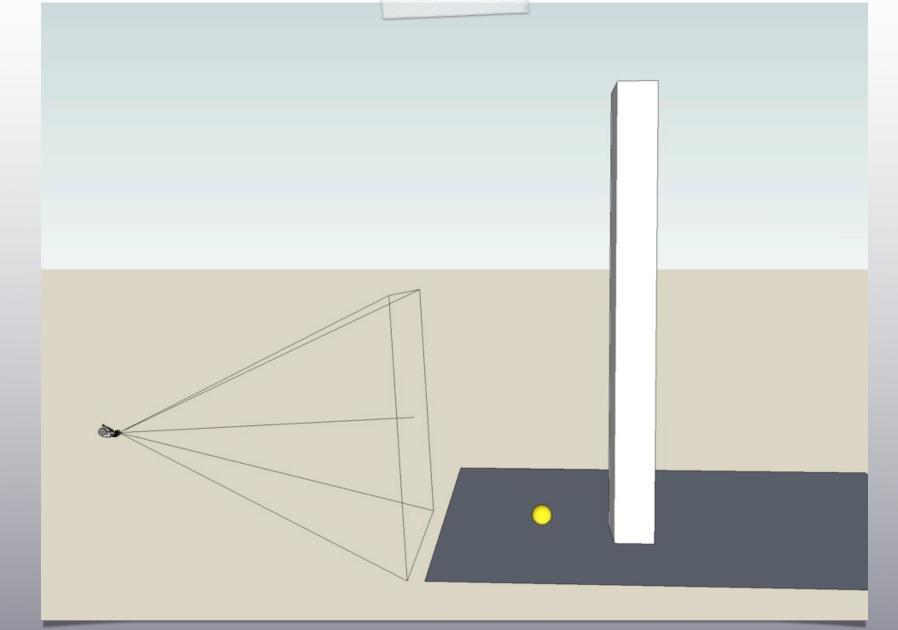
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System Hardware
Aspects of Software



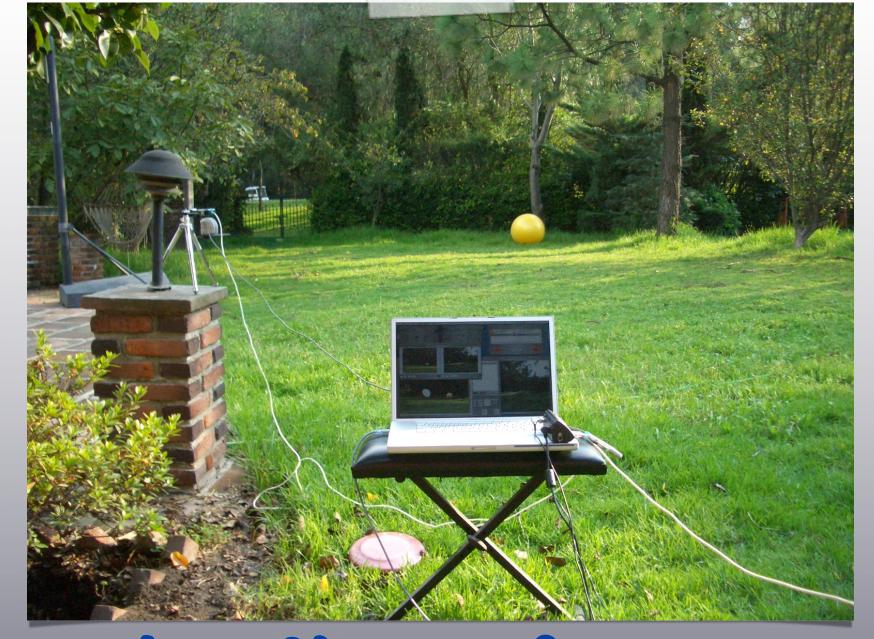
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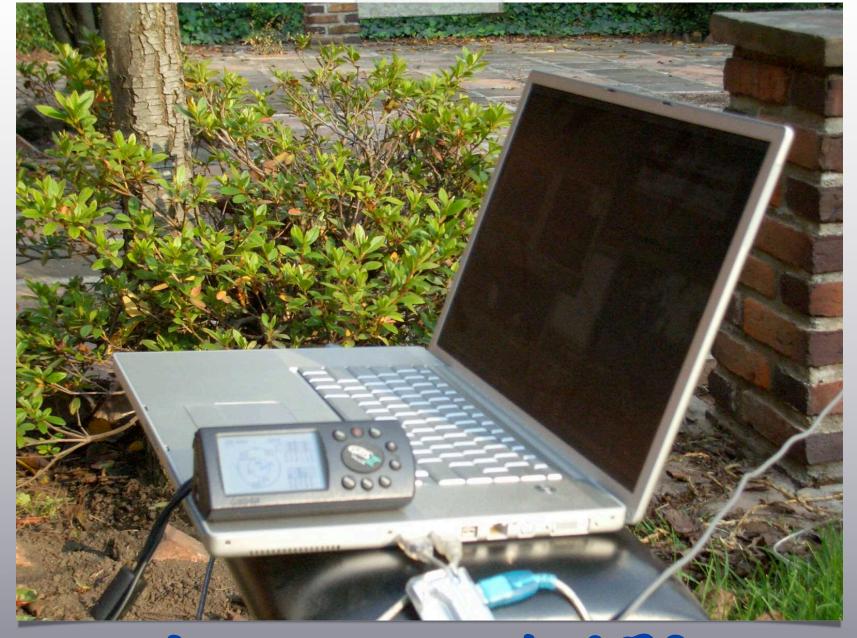


Principle Setup

Camera with viewing volume, model and fiduciary feature with Google SketchUp



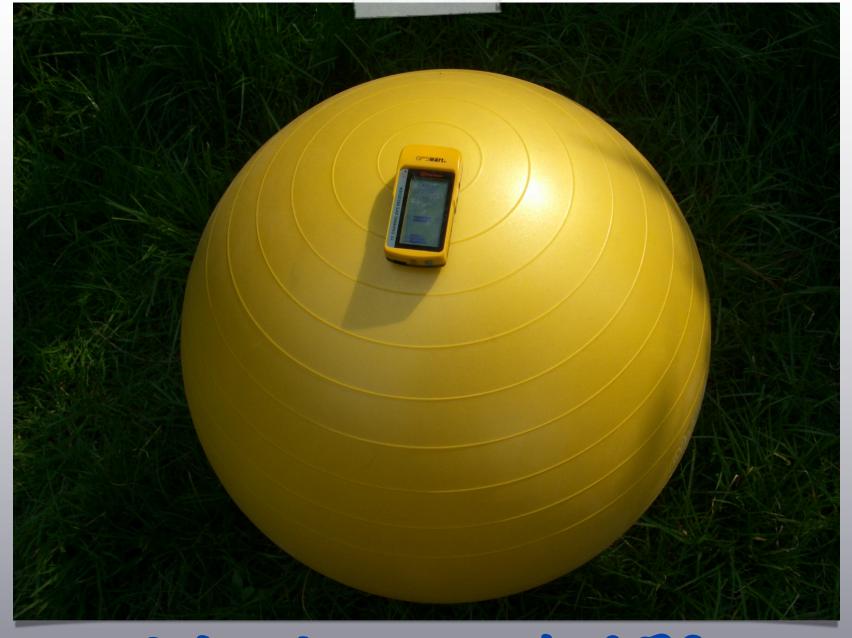
AmbiViewer-System System with laptop, camera, 2 GPS-receiver and marker Backyard in Mexico



Laptop with camera and GPS-receiver Backyard in Mexico



DV-camera with GPS DV-camera (zoom) with attached GPS-receiver Backyard in Mexico



Marker with GPS Marker ball as fiduciary feature Ball with attached Bluetooth GPS- receiver



Set of Hardware

Set with camera, 2 GPS-receiver and inflatable marker ball Everything fits in one bag.



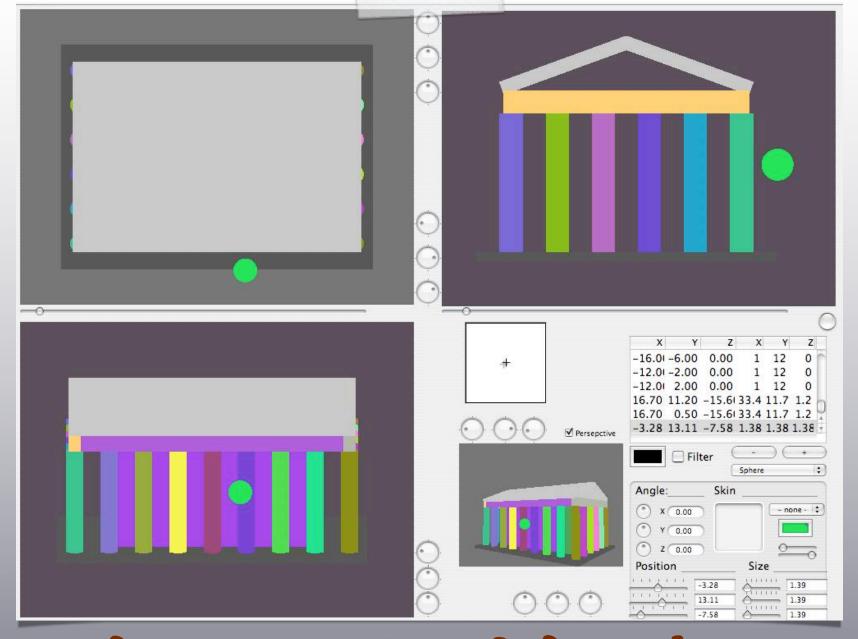
Usage The deployable system can be used almost everywhere. Fits in the bag.



Interface



Detection of the Marker Result Marker with overlaid circle

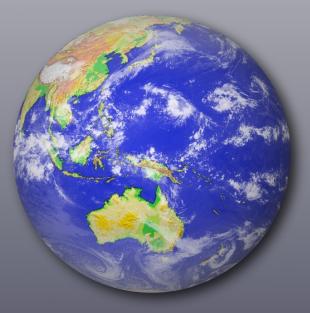


Interactive Modeler 3-view graphical interface Greek periopteros temple with marker



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System Hardware
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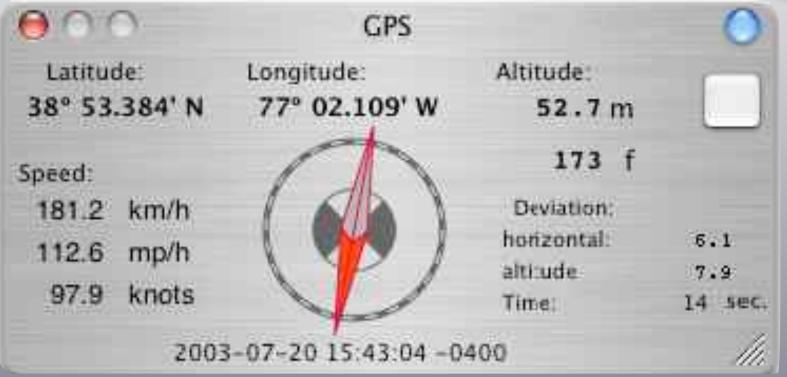
Usage

Two questions:

- Where am I? Positioning, used to add Informations
- Where is he/she/it? Tracking







Interface used for a single GPS-receiver

GPS Concept of satelite navigation

- Timebased signals
- Framing grid
- Geometric representation Ellipsoid as model of the Earth





Accuracy

Satelite reception

 Accuruacy depends solely on the number of used satelites in view.

- More accuracy is available with corrected informations based on other known positions
 - Differential GPS
 - second GPS-receivers

Nr		GPS		
1	Θ	/dev/cu.usbserial0	+	
2	θ	/dev/cu.USA19QI182273P1.1	4	
		get local Devices		

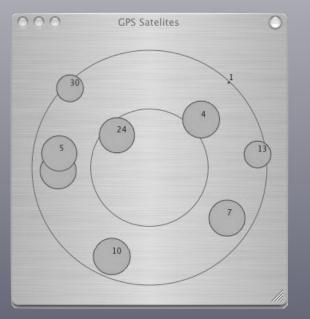


Multiple Devices connected to the computer

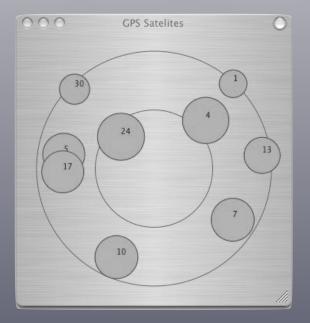
GPS

Satelites in view are almost the same













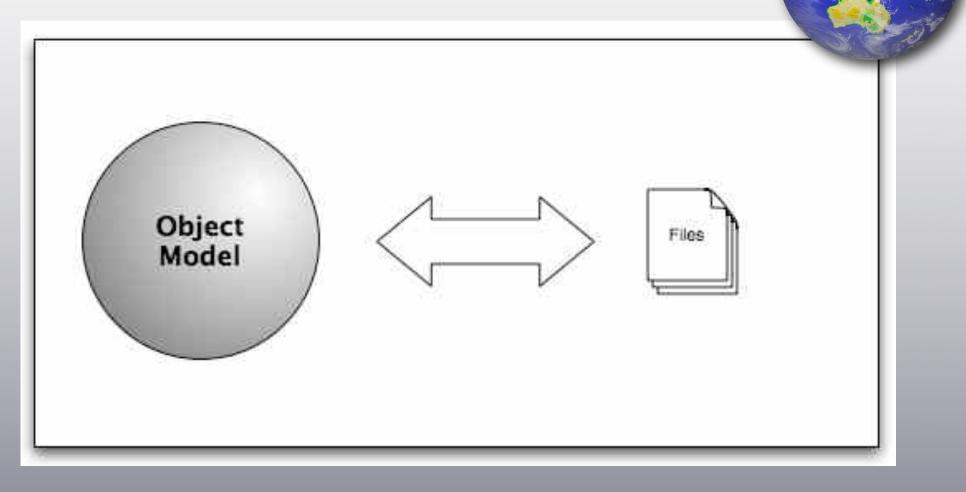
Transmission

Transmitting the signal from a remote GPS-receiver is difficult

Two approaches:

- Transmission over an IP-network using Distributed Objects. Additional computers and network installation necessary on site.
- Bluetooth technology Low range, commonly lower than 30 m.

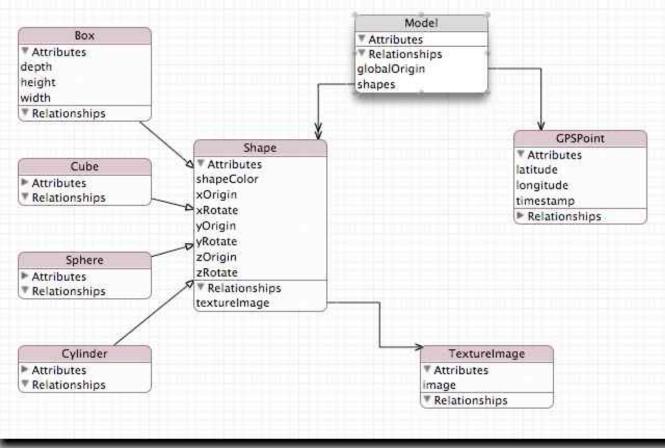




Model- data with GPS There is no file-format to store CAD-data with global coordinates, except Google.







Proposed data-model Layout for a proposed format with absolute coordinates

View of the satelites



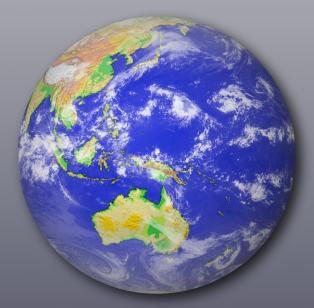
View of the satelites

View of the satelites



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Combining CAD and GPS



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Thank you



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